## Mathematical morphology: basic operators

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Graph-based mathematical morphology
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## ESIEE <br> PARIS



## Outline of the lecture

1 Operators: definitions and properties

2 Dilation and Erosion (by duality)

3 Algorithms

4 An open question?

## Operator

- $E$ is a set
- Let $X \subseteq E$, we denote by $\bar{X}$, the complementary set of $X$
- $\bar{X}=E \backslash X$
- We remark that $\overline{(\bar{X})}=X$


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## Definition

- An operator (on $E$ ) is a map from $\mathcal{P}(E)$ to $\mathcal{P}(E)$
- In the following $\gamma$ denotes an operator on $E$


## Dual

## Definition

- The dual of $\gamma$ is the operator $\star \gamma$ defined by
- $\forall X \subseteq E, \star \gamma(X)=\overline{\gamma(\bar{X})}$


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## Property

- $\star \star \gamma=\gamma$


## Dual: Example \#1

- Let $E$ be a metric space: $E$ is endowed with a given distance $d$
- Let $\gamma^{r}$ be the operator defined by
- $\forall X \in \mathcal{P}(E), \gamma^{r}(X)=\{x \in E \mid \exists y \in X, d(x, y) \leq r\}$


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■ We see that $\star \gamma^{r}(X)=\{x \in E \mid \forall y \in \bar{X}, d(x, y)>r\}$

- The set $\gamma^{r}(X)$ can be seen as a neighborhood of $X$ (of size $r$ ) and $\star \gamma(X)$ as an interior of $X$



## Dual: Exemple \#2 - convex hull

- Let $E$ be the Euclidean plan $E=\mathbb{R}^{2}$
- A subset $Y$ of $E$ is convex if any line segment whose extremities are in $Y$ is included in $Y$
- Let $X \subseteq E$ the convex hull of $X$ is the set
- ch $(X)=\cap\{Y \mid Y$ is convex and $X \subseteq Y\}$


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## Property

- Let $X \subseteq E$ be a bounded set, then $\star \operatorname{ch}(X)=\emptyset$.
- Is the converse also true?

NB: $X$ is bounded $\Leftrightarrow \exists$ a disc of finite radius that contains $X$

## Extensive operator

## Definition

- An operator $\gamma$ is extensive if
- $\forall X \subseteq E, X \subseteq \gamma(X)$
- An operator $\gamma$ is anti-extensive if
- $\forall X \subseteq E, \gamma(X) \subseteq X$


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## Property

- An operator $\gamma$ is extensive if and only if $\star \gamma$ is anti-extensive

Proof. $\gamma$ is extensive $\Leftrightarrow \forall X \subseteq E, \bar{X} \subseteq \gamma(\bar{X})$
Thus, $\forall X \subseteq E, X \supseteq \overline{\gamma(\bar{X})}$, which means that $\star \gamma$ is anti-extensive.

## Increasing and idempotent operators

## Definition

- An operator $\gamma$ is increasing if
- $\forall X, Y \in \mathcal{P}(E), X \subseteq Y \quad \Longrightarrow \gamma(X) \subseteq \gamma(Y)$
- An operator $\gamma$ is idempotent if
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## Property

- $\gamma$ is increasing $\Leftrightarrow \star \gamma$ is increasing

■ $\gamma$ is idempotent $\Leftrightarrow \star \gamma$ is idempotent

Example. Are the operators of previous examples extensive, increasing and idempotent?

## Algebraic dilation and erosion

## Definition

- Let $\delta$ and $\epsilon$ be two operators
$\square \delta$ is an (algebraic) dilation whenever it commutes under union:
■ $\forall X, Y \in \mathcal{P}(E), \delta(X) \cup \delta(Y)=\delta(X \cup Y)$
$■ \epsilon$ is an algebraic erosion whenever it commutes under intersection:
- $\forall X, Y \in \mathcal{P}(E), \epsilon(X) \cap \epsilon(Y)=\epsilon(X \cap Y)$


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## Property

- $\delta$ is a dilation if and only if $\star \delta$ is an erosion
- $\delta$ and $\epsilon$ are increasing


## Example

■ The neighborhood operator $\gamma^{r}$ of size $r$ is a dilation

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## Exercice.

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- The convex hull operator ch is not a dilation


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■ Thus, the operator $\star$ ch is not an erosion

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## Discrete morphology

## Problem

- How can we define an operator that can handle geometric data (such as images for instance) stored in a computer memory?
- How can we efficiently implement such operators?


## Morphological dilation

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- $\delta_{\Gamma}(X)=X \oplus \Gamma=\cup\{\Gamma(x) \mid x \in X\}$


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Remark. Any morphological dilation is an algebraic dilation
Straightforward property.
$\delta_{\Gamma}$ is extensive if and only if $(E, \Gamma)$ is reflexive
Thus, $\star \delta_{\Gamma}$ is anti-extensive if and only if $\Gamma$ is reflexive

## Example in an arbitrary graph



- $\delta_{\Gamma}(X)=?$


## Example in an arbitrary graph


$X=\{a, b, c, d, g, k\} \quad \delta_{\Gamma}(X)=X \cup\{e, l, m\}$

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## Example in an arbitrary graph


$X=\{a, b, c, d, g, k\} \quad \delta_{\Gamma}(X)=X \cup\{e, I, m\} \quad \star \delta_{\Gamma}(X)=X \backslash\{k, a\}$

- $\delta_{\Gamma}(X)=?$
$\square \star \delta_{\Gamma}(X)=$ ?


## Mesh: example



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## Translation invariant structuring element

■ Let $E$ be a subset of a space endowed with a translation $\mathcal{T}$

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- Let $x \in E$ and $\overrightarrow{y z} \in E \times E$, we denote by $\mathcal{T}_{\overrightarrow{y z}}(x)$ the translation of $x$ by the vector $\overrightarrow{y z}$
- Let $X \in \mathcal{P}(E)$, the translation of $X$ by $\overrightarrow{y z}$ is the set:
- $\mathcal{T}_{\vec{y} \mathbf{z}}(X)=\left\{\mathcal{T}_{\vec{y} \vec{z}}(x) \mid x \in X\right\}$


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■ A structuring element $\Gamma$ on $E$ is translation invariant if

- $\forall x, y \in E, \Gamma(y)=\mathcal{T}_{\overrightarrow{x y}}(\Gamma(x))$


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- A structuring element $\Gamma$ on $E$ is translation invariant if
- $\forall x, y \in E, \Gamma(y)=\mathcal{T}_{\overrightarrow{x y}}(\Gamma(x))$


## Remark.

1 In order to define a translation invariant structuring element, defining $\Gamma(x)$ at a unique point $x \in E$ is sufficient
2 If $\Gamma$ is translation invariant, then $\forall X \in \mathcal{P}(E), \forall \vec{v} \in E \times E$, $\delta_{\Gamma}\left(\mathcal{T}_{\vec{v}}(X)\right)=\mathcal{T}_{\vec{v}}\left(\delta_{\Gamma}(X)\right)$

## Example: square grid

- Let $E=\mathbb{Z}^{2}$ and $\Gamma$ be defined by $\forall x=(i, j) \in \mathbb{Z}^{2}$,

$$
\Gamma(x)=\{(i, j),(i+1, j),(i+1, j-1),(i, j-1),(i-1, j-1)\}
$$



## Questions.

1. Use the representation above to draw the structuring elements $\Gamma^{-1}$ and $\Gamma_{s}$ (symmetric closure of $\Gamma$ ).
2. Draw $\delta_{\Gamma}(X), \delta_{\Gamma-1}(X), \delta_{\Gamma_{s}}(X), \star \delta_{\Gamma}(X), \star \delta_{\Gamma-1}(X)$, and $\star \delta_{\Gamma_{s}}(X)$.

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2D imagery: example

,



## 3D imagery: example





## Morphological dilation and erosion: characterizations

## Property

- Let $\Gamma$ be a structuring element and let $X \subseteq E$

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1 \delta_{\Gamma}(X)=\left\{x \in E \mid \Gamma^{-1}(x) \cap X \neq \emptyset\right\}
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## Morphological dilation and erosion: characterizations

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## Proof.

$1 \delta_{\Gamma}(X)=\cup\{\Gamma(x) \mid x \in E\}=\{y \in \mid \exists x \in X, y \in \Gamma(x)\}$ $=\left\{y \in \mid \exists x \in X, x \in \Gamma^{-1}(y)\right\}=\left\{y \in E \mid \Gamma^{-1}(y) \cap X \neq \emptyset\right\}$

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## Proof.

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\begin{aligned}
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& \quad=\left\{y \in \mid \exists x \in X, x \in \Gamma^{-1}(y)\right\}=\left\{y \in E \mid \Gamma^{-1}(y) \cap X \neq \emptyset\right\}
\end{aligned}
$$

$2 \star \delta_{\Gamma}(X)=\overline{\delta(\bar{X})}$. Thus, by 1 , we deduce :

$$
\begin{aligned}
& \star \delta_{\Gamma}(X)=\left\{x \in E \mid \Gamma^{-1}(x) \cap \bar{X} \neq \emptyset\right\} \\
& \star \delta_{\Gamma}(X)=\left\{x \in E \mid \Gamma^{-1}(x) \cap \bar{X}=\emptyset\right\} \\
& \left.\star x \in E \mid \Gamma^{-1}(x) \subseteq X\right\}
\end{aligned}
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## Influence of the structuring element

Question. Erode the set $X$ represented in black by the structuring element $\Gamma$, that is to say draw $\star \delta_{\Gamma}(X)$


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## Structuring elements

- The result of a dilatation/erosion highly depends on the structuring elements that can be
- of various shapes
- of various sizes
- isotropic or not
- symmetric or not
- reflexive or not

■ convex or not

- translation invariant or not


## Computing a morphological dilation

## Algorithm DIL (Data: $(E, \Gamma), X \subseteq E ;$ Result: $Y=\delta_{\Gamma}(X)$ )

- $Y:=\emptyset$;
- For each $x \in X$ do
- For each $y \in \Gamma(x)$ do $Y:=Y \cup\{y\} ;$


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## Complexity

- Algorithm DIL can be implemented to run in $O(n+m)$ time, where $n=|E|$ and $m=|\bar{\Gamma}|$
- Which data structure for $(E, \Gamma), X$ and $Y$ ?


## Union of structuring elements

## Property

- Let $\Gamma_{1}, \Gamma_{2}$ and $\Gamma_{3}$ be three structuring elements such
that $\overrightarrow{\Gamma_{3}}=\overrightarrow{\Gamma_{1}} \cup \overrightarrow{\Gamma_{2}}$
- $\forall X \in \mathcal{P}(E)$,
$1 \delta_{\Gamma_{3}}(X)=\delta_{\Gamma_{1}}(X) \cup \delta_{\Gamma_{2}}(X)$
$2 \star \delta_{\Gamma_{3}}(X)=\star \delta_{\Gamma_{1}}(X) \cap \star \delta_{\Gamma_{2}}(X)$


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## Proof.

$1 \delta_{\Gamma_{3}}(X)=\cup\left\{\Gamma_{3}(x) \mid x \in X\right\}$ Thus, by union of graphs,
$\delta_{\Gamma_{3}}(X)=\cup\left\{\Gamma_{1}(x) \cup \Gamma_{2}(x) \mid x \in X\right\}$
$=\left[\cup\left\{\Gamma_{1}(x) \mid x \in X\right\}\right] \cup\left[\cup\left\{\Gamma_{2}(x) \mid x \in X\right\}\right]=\delta_{\Gamma_{1}}(X) \cup \delta_{\Gamma_{2}}(X)$
2 By duality, $\star \delta_{\Gamma_{3}}(X)=\overline{\delta_{\Gamma_{3}}(\bar{X})}$. Thus, from relation 1 ., $\star \delta_{\Gamma_{3}}(X)=\overline{\left.\delta_{\Gamma_{1}}(\bar{X}) \cup \delta_{\Gamma_{2}}(\bar{X})\right\}}=\overline{\delta_{\Gamma_{1}}(\bar{X})} \cap \overline{\left.\delta_{\Gamma_{2}}(\bar{X})\right\}}$. Hence, by duality, $\star \delta_{\Gamma_{3}}(X)=\star \delta_{\Gamma_{1}}(X) \cap \star \delta_{\Gamma_{2}}(X)$

## Dilations of structuring elements

## Definition

- Let $\Gamma_{1}$ and $\Gamma_{2}$ be two structuring elements
- We denote by $\Gamma_{1} \oplus \Gamma_{2}$ the structuring element such that
- $\forall x \in E, \Gamma_{1} \oplus \Gamma_{2}(x)=\delta_{\Gamma_{2}}\left(\Gamma_{1}(x)\right)$


## Composition of dilations by structuring elements

## Property

- Let $\Gamma_{1}$ and $\Gamma_{2}$ be two structuring elements
$1 \forall X \in \mathcal{P}(E), \delta_{\Gamma_{1} \oplus \Gamma_{2}}(X)=\delta_{\Gamma_{2}}\left(\delta_{\Gamma_{1}}(X)\right)$
$2 \forall X \in \mathcal{P}(E), \star \delta \delta_{\Gamma_{1} \oplus \Gamma_{2}}(X)=\star \delta_{\Gamma_{2}}\left(\star \delta_{\Gamma_{1}}(X)\right)$


## Proof.

$1 \delta_{\Gamma_{1} \oplus \Gamma_{2}}(X)=\cup\left\{\Gamma_{1} \oplus \Gamma_{2}(x) \mid x \in X\right\}=\cup\left\{\delta_{\Gamma_{2}}\left(\Gamma_{1}(x)\right) \mid x \in X\right\}$.
Since $\delta_{\Gamma_{2}}$ is an algebraic dilation, $\delta_{\Gamma_{2}}$ commutes under union.
Hence, $\left.\delta_{\Gamma_{1} \oplus \Gamma_{2}}(X)=\delta_{\Gamma_{2}}\left(\cup\left\{\Gamma_{1}(x) \mid x \in X\right\}\right)=\delta_{\Gamma_{2}}\left(\delta_{\Gamma_{1}}\right)(X)\right)$
2 The second relation follows from the first one by duality.

## Decomposition of structuring elements

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■ This can lead to a significant efficiency improvement of some dilation algorithms

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- This can lead to a significant efficiency improvement of some dilation algorithms


But $\Gamma_{4}=\bullet \cdot$ cannot be decomposed

## Iterated operators

## Definition

- Let $\gamma$ be an operator and let $i \in \mathbb{N}$
- $\gamma^{i}$ is the operator defined by

$$
\begin{aligned}
& 1 \gamma^{i}=\gamma \gamma^{i-1} \\
& \left.2 \gamma^{0}=I d \quad \text { (i.e. } \forall X \subseteq E, \gamma^{0}(X)=X\right)
\end{aligned}
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## Iterated operators

## Definition

- Let $\gamma$ be an operator and let $i \in \mathbb{N}$
- $\gamma^{i}$ is the operator defined by

$$
\begin{aligned}
& 1 \gamma^{i}=\gamma \gamma^{i-1} \\
& \left.\mathbf{2} \gamma^{0}=I d \text { (i.e. } \forall X \subseteq E, \gamma^{0}(X)=X\right)
\end{aligned}
$$

## Property

$\square \star\left[\gamma^{i}\right]=[\star \gamma]^{i}$

- Let $\Gamma$ be a structuring element, $\left[\delta_{\Gamma}\right]^{i}=\delta_{\Gamma \oplus \ldots \oplus \Gamma}$


## Exercise

- Let $E=\mathbb{Z}^{2}$ and let $\Gamma_{4}$ be defined by $\forall x=(i, j) \in E, \Gamma_{4}(x)=$ $\{(i, j),(i-1, j),(i, j-1),(i+1, j),(i, j+1)\}$
■ How many elements belong to $\Gamma_{4} \oplus \Gamma_{4} \oplus \Gamma_{4}(x)$, for any $x \in E$ ?
- Compare approximately the number of operations required to compute $\delta_{\Gamma_{4} \oplus \Gamma_{4} \oplus \Gamma_{4}}$ and $\left[\delta_{\Gamma_{4}}\right]^{3}$ by using algorithm DIL
- Indication: you can consider that DIL uses $n+m$ operations to perform a dilation by a structuring element $\Gamma_{4}$ (with $n=|E|$ and $m=\left|\overrightarrow{\Gamma_{4}}\right|$ )


## Exercise

■ Let $X \subseteq \mathbb{Z}^{2}$ be the black object drawn below

- Which operator (or composition of operators) can you use to suppress the horizontal wire while preserving the vertical ones?
- Which operator (or composition of operators) allows the "hole" of $X$ to be filled in while minimizing the difference between the result and $X$ ?



## Exercise

- Let $E=\mathbb{Z}^{2}$, let $X \subseteq E$, and let $\overrightarrow{x y} \in E \times E$ be any vector of $\mathbb{Z}^{2}$, with $x=\left(i_{x}, j_{x}\right)$ and $y=\left(i_{y}, j_{y}\right)$
- The morphological machine can only perform the following operations
- dilation by a structuring element
- complementation
- Is it possible to compute the translation of $X$ by $\overrightarrow{x y}$ with the morphological machine?
- Same question for a restricted morphological machine for which the structuring elements must be included in $\Gamma_{4}$


## Adjunction

## Problem

- Is there an inverse operator $\delta^{\prime}$ for any dilation $\delta$ ?
- In other words, can we find $\delta^{\prime}$ such that $\forall X \in \mathcal{P}(E), \delta^{\prime}(\delta(X))=X$ ?


## Solution

- Come to next lecture about mathematical morphology!


## List of main notions

■ Increasing, extensive, anti-extensive idempotent operators

- Dual operators
- Algebraic dilation/erosion
- Morphological dilation/erosion (by a structuring element)

